

state-when-first^{11,40}

$\forall es:\text{event_system}\{i:l\}, e:\text{es-E}(es).$

$(\uparrow\text{es-first}(es; e))$

$\Rightarrow \text{sqequal}(\text{es_state_when}(es; e); (\lambda x,t. \text{es_init}(es)(\text{loc}(e),x,t + \text{es-time}(es; e))))$